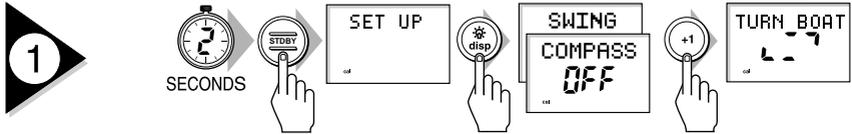


Distributed by
Raymarine

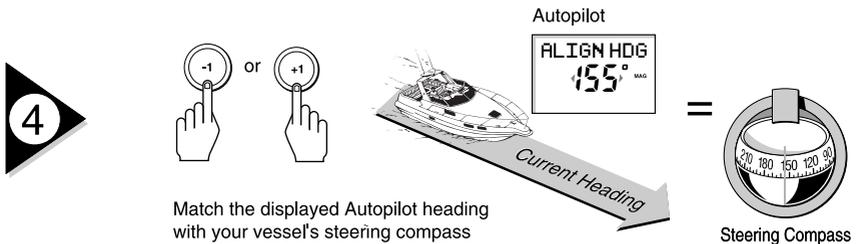
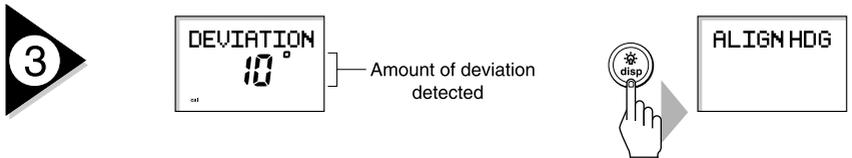
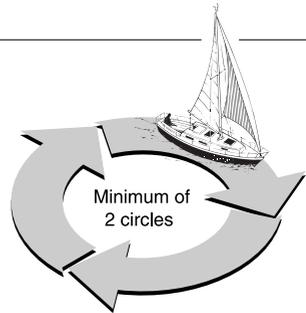
Any reference to Raytheon or RTN in this manual should be interpreted as Raymarine. The names Raytheon and RTN are owned by the Raytheon Company.

ST4000, 5000 & 6000 Plus Compass Deviation Correction & Heading Alignment

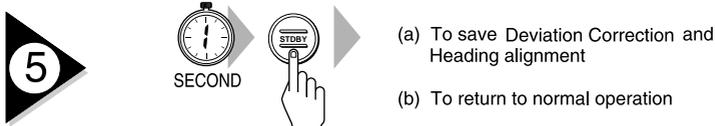


- 2
- (a) Turn your boat in circles
 - (b) Keep your boat speed below 2 knots
 - (c) Keep turning your boat until the deviation screen is displayed (see 3 below)

Note: One complete circle should take at least 3 minutes



Match the displayed Autopilot heading with your vessel's steering compass

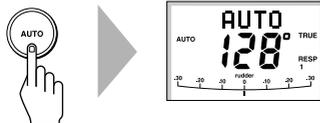


ST4000, 5000 & 6000 Plus

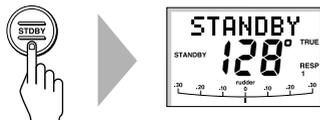
Quick Reference Guide to Basic Operation

This is only a quick reference guide to basic operation and calibration (overleaf). For full details, please refer to the appropriate chapters in the Operation and Installation handbook.

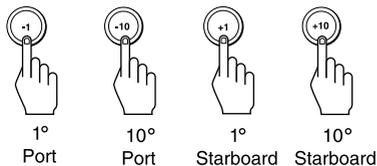
Engaging the Autopilot (Auto mode)



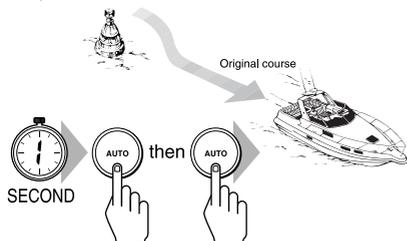
Disengaging the Autopilot (Standby mode)



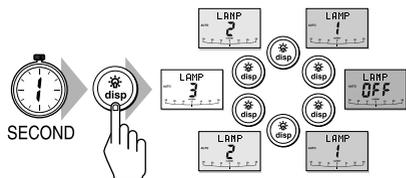
Making course changes in Auto mode



Returning to the previous Autopilot heading after a dodge manoeuvre executed with the pilot in Auto mode

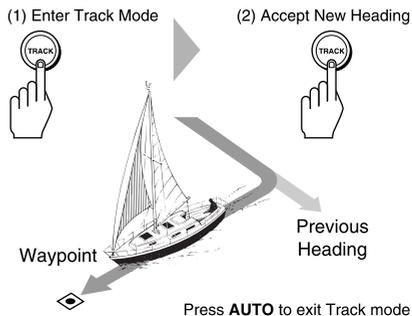


Illumination - Switching ON/OFF and Making Adjustments

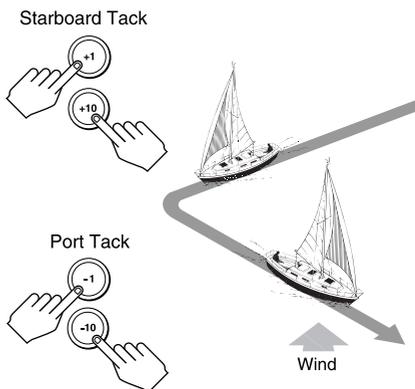


The display times-out to normal operation after 7 seconds of keypad inactivity.

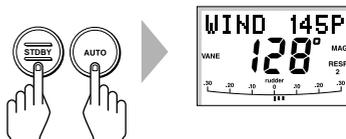
Engaging Track Mode from Auto



Engaging the Automatic Tack Feature



Selecting Vane mode (WindTrim) from Standby and Auto modes



Returning to the previous apparent wind angle (e.g. after a dodge manoeuvre)

